Notes for CV Research

* Investigating Object Detection as a means of self driving
* Will be looking into pre-trained models that we can use our small dataset to back propagate over.
* We may want to couple the image input with a steering input as well
* chrome-extension://oemmndcbldboiebfnladdacbdfmadadm/http://syedurrahman.tripod.com/obstacle\_detection.pdf
* <https://www.quora.com/Where-will-I-get-a-labeled-image-dataset-for-obstacle-detection-on-roads>
* <https://tev.fbk.eu/databases/diplodoc-road-stereo-sequence>
* <http://www.cvlibs.net/datasets/kitti/eval_road.php>
* <http://synthia-dataset.net/download-2/>
* chrome-extension://oemmndcbldboiebfnladdacbdfmadadm/https://arxiv.org/pdf/1606.02228v2.pdf
* <https://www.quora.com/Are-small-training-data-sets-1000-4000-cases-with-200-1000-dimensions-adequate-for-constructing-robust-deep-learning-neural-networks-for-regression>
* <https://github.com/takeitallsource/awesome-autonomous-vehicles>
* <http://robotcar-dataset.robots.ox.ac.uk/>